

From point cloud to BIM

Dr. Matthias Kunz Business Development Manager Plant, kubit GmbH (matthias.kunz@kubit.de)





- Germany based software developer
- Headquarter in Dresden, Partner office in USA
- Started 1999, today 25 people
- A complete "From Real World to CAD" portfolio with software for laser scanning, photogrammetry and total stations
- ~ 2.300 customers with ~ 5.500 licenses worldwide







AutoCAD based products





Stand alone product

CAD-specific connectors





- Point clouds are perfect for as-built condition surveying. But they are not intelligent in itself. "Simple" XYZ measurements.
 - \rightarrow Intelligent, parameterised, CAD objects wanted for planning
 - → BIM: Plan, Design, Construct, Operate (Cost, Bill of quantities, etc.)
 - \rightarrow BIM works with (intelligent) object classes and families
 - \rightarrow 4D (time), 5D (cost)
- Laserscanning shadow causes incomplete object coverage
 - \rightarrow Complete models needed, e.g. visualisation, clash detection
- Point clouds are not water-tight
 - ightarrow 3D meshing or printing require "water-tight" models



- Point cloud data consumes large amounts of data
 - \rightarrow Reduction of data and simple exchange of BIM models
- A point cloud is not a BIM model
 - → BIM needs one model basis for BIM process (Planning, Design, Construction, Mangement)

 \rightarrow Conversion from point cloud to BIM required!



"The adoption of the directive, officially called the European Union Public Procurement Directive (EUPPD) means that all the 28 European Member States may encourage, specify or **mandate the use of BIM for publicly funded construction and building projects in the European Union by 2016.** The UK, Netherlands, Denmark, Finland and Norway already require the use of BIM for publicly funded building projects."



AUTODESK.

Source: http://inthefold.autodesk.com/in_the_fold/2014/01/european-parliament-directive-to-spur-bim-adoption-in-28-eu-countries.html





Two different initial situations





Visibility

- View dependent control
- Choose between different color options
- Hide point cloud or only different scans (if you use a rcp project with scan positions!)



skubit

skubit

Visibility

| Architecture Structure Systems Inse | t Annotate Analyze Massing & Site Collaborate View Manad | ge |
|-------------------------------------|---|--|
| | Wisibility/Graphic Overrides for 3D View: (3D) | |
| | Model Categories Annotation Categories Analytical Model Categories Imported Categories Filt | ers Point Clouds |
| Templatet Graphics Lines | It I Show point clouds in this view | If a point cloud is unchecked, it will not be visible. |
| | Visibility | Color Mode |
| | E DiCarlo_Office_090713_scan_020.rcp | RGB |
| | DiCarlo_Office_090713_scan_001 | <no override=""></no> |
| | DiCarlo_Office_090713_scan_002 | <no override=""></no> |
| | DiCarlo_Office_090/13_scan_003 | <no override=""></no> |
| | DiCarlo_Office_090713_scan_004 | <no override=""></no> |
| | | <no override=""></no> |
| | DiCarlo_Office_000713_scan_007 | <no override=""></no> |
| | Dicarlo Office : | |
| | DiCarlo Off | <no override=""></no> |
| | DiCarlo_Off Delate Diselar | <no override=""></no> |
| | DiCarlo_Off | <no override=""></no> |
| | DiCarlo_Off Color Mode: RGB | No Override> |
| | | <no override=""></no> |
| | DiCarlo_Off Settings Single Color | <no override<="" th=""></no> |
| | DiCarlo_Off | <no override=""></no> |
| | DiCarlo_Off Normals | <no override=""></no> |
| | DiCarlo_Off | <no overide=""></no> |
| | DiCarlo_Off | <no override=""></no> |
| | | <no override=""></no> |
| | | |
| | Clear Overrides OK | Cancel |
| | | |
| | Select All | |
| | | |
| | OK OK | Abbrechen Übernehmen Hilfe |
| | Au. | |



Behavior

- Like any other model object
 - → Select, Move, Rotate, Mirror (if you have a good reason for that!)
- Point cloud snapping







Behavior

Clipped by section boxes and view ranges like any other model object



Example: Modelling a Roof with In-Place Mass



Software for surveying and as-built documentation www.kubit-software.com

skubit



- No real 3d point snapping
 → Snapping works only in the active work plane
- No scan view available
 - \rightarrow Often more intuitive and easier navigation
- No point cloud support in the family environment

 Necessary to create individual building components

skubit

- No real 3d point snapping
 Snapping works only in the active work plane
- No scan view available

 Often more intuitive and easier navigation



- No point cloud support in the family en
 - → Necessary to create individual building components



Create CAD drawings

- Send coordinates, distances, (commands) to any CAD system.
- By measuring and clicking in the scan the geometry is drawn.





Scan view

VirtuSurv extends Revit with panorama scan views
 → Create BIM elements (walls, windows ...) or generic elements (lines, points ...) inside the photo like Scan View



VirtuSurv Revit Link



BIM modeling with the Revit link of VirtuSurv for generating

- architectural BIM elements
- 3D construction helpers
- directly inside Revit



VirtuSurv Revit Link



Creating BIM elements

- Fast generating of levels, walls, doors, windows and openings
- Most elements by just 2 clicks





Point Modes for accurate element construction



- Point perpendicular to active work plane
- Intersection Point
- Usable with nearly all VirtuSurv for Revit commands





2D and 3D Construction helpers

 Use 2D detail lines, 3D model lines or 3D construction points to generate other shapes





VirtuSurv Revit Link



Revit point cloud link

- Create a Revit point cloud and a VirtuSurv project from the same registered scan project
- 2. Link the Revit point cloud to the VirtuSurv project



VirtuSurv Revit Link



Revit point cloud link

- 3. Move and rotate the Revit point cloud to the position you need
- 4. Use VirtuSurv with the new point cloud position





Precision



BIM Intelligence

What can we expect in the future?







Tasks for the future:

- 1. Automatic recognition of building elements in point clouds
 - Precise shape and position of 3D building elements



- 2. Consideration of design conditions
 - Orthogonal wall axes
 - Minimal number of differnt building element types
 - Compliance of wall alignment



skubit



